

# Statistics for counting experiments

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# Probability

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- ◆ Frequency theory of probability

- $\text{Prob}(\text{event}) = \frac{\text{How many times event happened}}{\text{How many opportunities for it to happen}}$
- Unless denominator is large (*high statistics experiment*), we have only a relatively poor **estimate** of the "true" probability -- assumed to be due to some underlying "law"

# Man-in-the-Street views of probability

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## ◆ Fallacies about denominators

- "90% of our flights arrive on time"
  - » correct statement: "flights delayed several hours are cancelled, not 'delayed', so they get excluded from our average"
- "The average worker is making 10% more now than he was 10 years ago"
  - » correct statement: "the minimum wage has risen, and more low-income people are unemployed"

## ◆ Fallacies about independence

- "This slot machine hasn't paid off in a long time, so I'm sure to win soon"
  - » correct statement: "If this slot machine is truly random, i am no more likely to win on the next try as at any other time"
- "Nobody's won the state lottery in a long time, so it is more likely to happen this week"
  - » correct statement: "Nobody's won the state lottery in a long time, so the payoff is bigger"

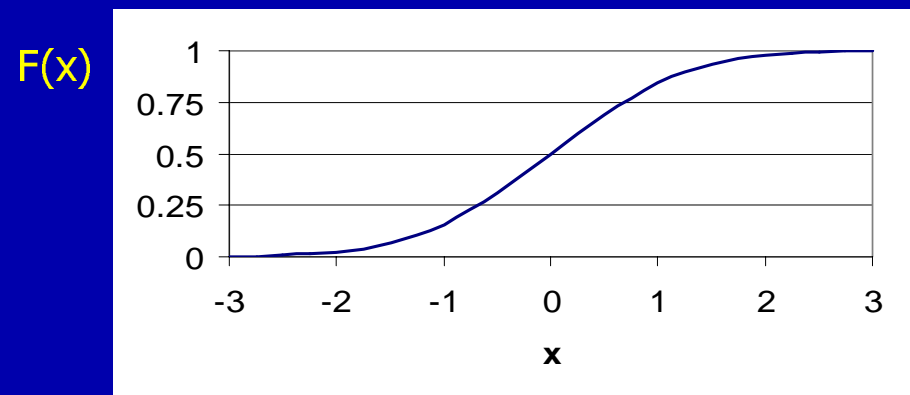
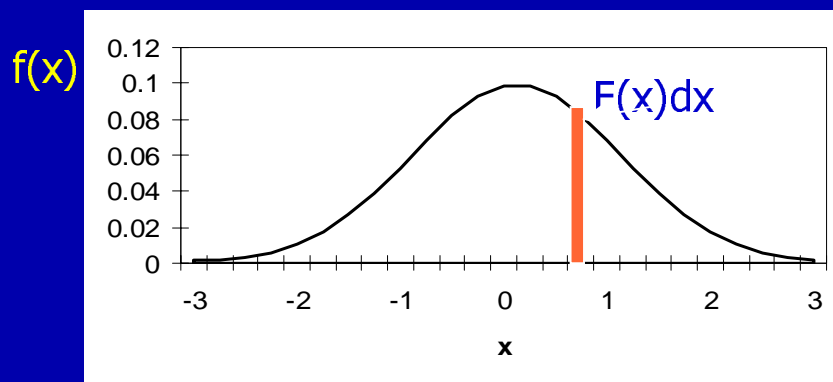
## ◆ ...or both combined

- "Our survey shows most people lose 10 pounds in a month on this diet"
  - » correct statement: "happy customers who lost weight were most likely to respond to our survey; the ones who gained weight most likely threw away our postcard..."

# Probability distributions and PDFs

- ◆ Probability Density Function (PDF) =  $f(x)$ 
  - probability of  $x$  in range  $x'$  to  $x'+dx$
- ◆ “Probability distribution” =  $F(x)$ 
  - *cumulative* or *integral* distribution = probability of  $x < x'$

$$F(x) = \int_{x_{MIN}}^x f(x)dx \quad (\text{where } x_{MIN} \text{ could be } -\infty)$$



# Descriptive parameters for PDFs

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- ◆ Measures of **central location**:
  - mean  $\langle x \rangle = \sum x_i / N$  (*sample mean*)
  - median =  $x$  at which  $F(x)=0.5$
  - mode =  $x$  at which  $f(x)=\text{maximum}$
  - for symmetrical distributions, mean=median
  
- ◆ Measures of **width** of distributions:
  - variance*  $\sigma^2$  ( $\sigma = \text{standard deviation}$ )
  - $\sigma^2 = \sum (x_i - \mu_1)^2 / N$
  - but  $\mu_1 = \text{mean of true PDF}$
  - we can only *estimate*  $\mu_1$  with  $\langle x \rangle$
  - Best estimator for  $\sigma^2$  is
  - $s^2 = \sum (x_i - \langle x \rangle)^2 / (N - 1) = \text{sample variance}$

# Counting statistics

- ◆ We have a **set of data** = N measurements of some sort:

$$\{ x_1 x_2 x_3 \dots x_N \}$$

- ◆ **Statistic** = a function of the data only - no unknown parameters

examples:

- **Sample mean** (experimental mean)

$$\bar{x} = \frac{1}{N} \sum_1^N x_i$$

- **Median**

sort the data in ascending or descending order

median = the (N/2)th entry in this list  $x_{MED} = x_{\frac{N}{2}}$  in  $sort_{\uparrow}(\{x_i\})$

- **Mode**

» Value with maximum probability density: location of peak of PDF

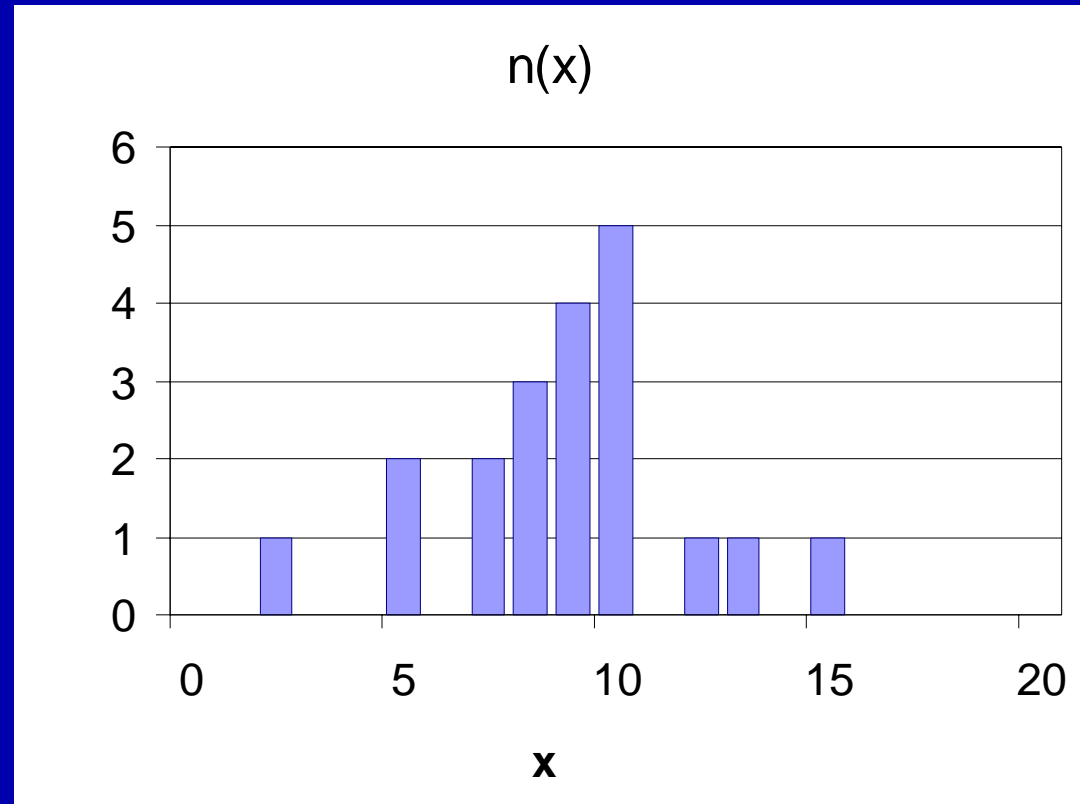
$$x_i \text{ such that } P(x_i) = \max P(x)$$

# Example: 20 sets of 1 minute counts

$x_k, k=0\dots 20:$

$k$	$x_k$
0	0
1	9
2	10
3	13
4	10
5	9
6	9
7	9
8	15
9	2
10	10
11	12
12	10
13	8
14	5
15	5
16	10
17	7
18	7
19	8
20	8

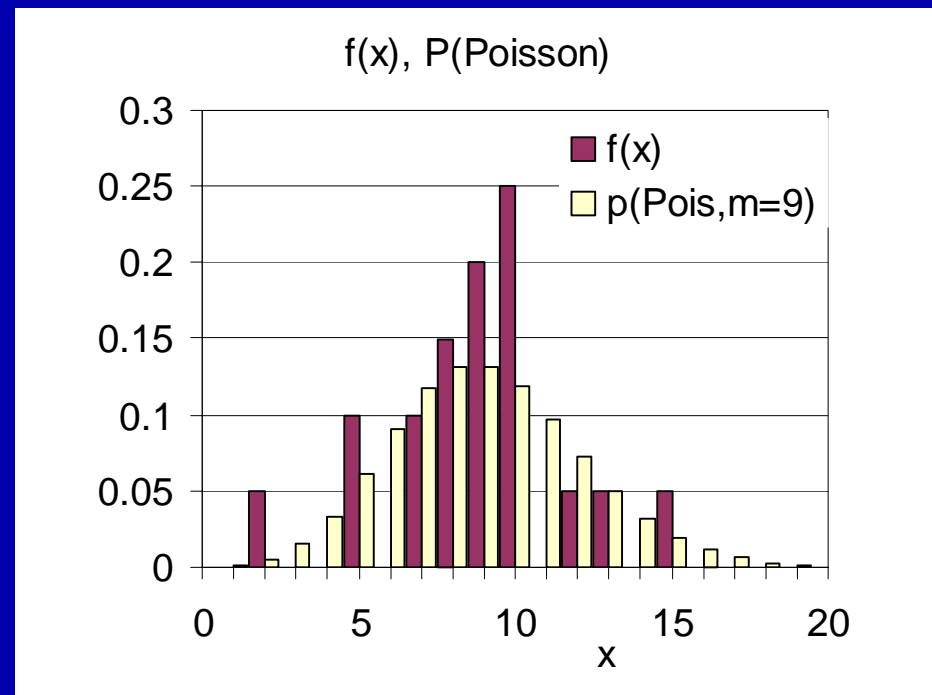
Histogram of the data:  
A bar graph showing how often each possible count value occurred



# Frequency distribution

<u>x</u>	<u>n(x)</u>	<u>f(x)</u>
0	0	0
1	0	0
2	1	0.05
3	0	0
4	0	0
5	2	0.1
6	0	0
7	2	0.1
8	3	0.15
9	4	0.2
10	5	0.25
11	0	0
12	1	0.05
13	1	0.05
14	0	0
15	1	0.05
16	0	0
17	0	0
18	0	0
19	0	0
20	0	0

- Use the histogram to *estimate* probability of each possible  $x$  value:  $f(x)=n(x)/N$
  - This is the **Probability Density Function (PDF)** or differential probability distribution
- (also shown below is the Poisson probability density function for mean value = 9 -- more on this later)





# Statistics of the data set

◆ sample mean:

sum of data: 176

sample mean = sum/20: 8.8

◆ sample variance:

sorted data

k	x	k
0	0	
1	2	
2	5	
3	5	
4	7	
5	7	
6	8	
7	8	
8	8	
9	9	
10	9	
11	9	
12	9	
13	10	
14	10	
15	10	
16	10	
17	10	
18	12	
19	13	
20	15	

◆ median=9

← median

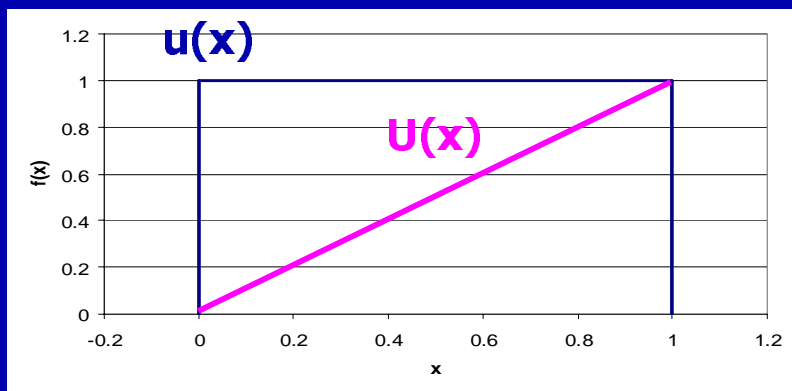
# Some famous probability distributions and their applications

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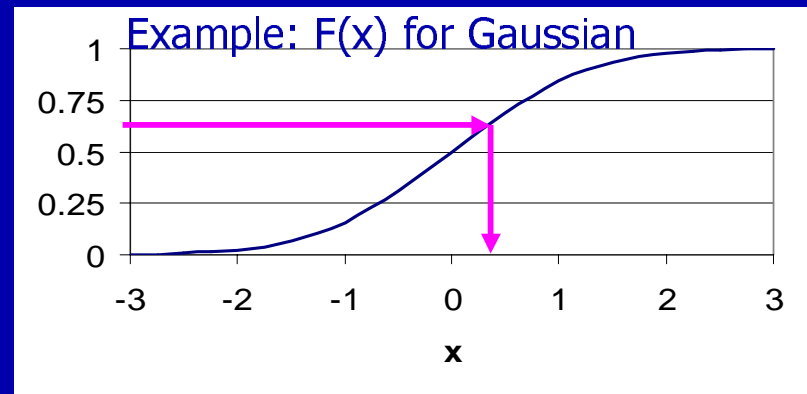
- ◆ Uniform
  - basis for generating numbers for simulations (computer pseudo-random number generators)
- ◆ binomial
  - Yes/No situations
- ◆ Poisson
  - Many physics applications
  - Applies when  $P(\text{event})$  is "small" and "independent of previous history"
- ◆ Gaussian (Normal)
  - Applies to results produced a series of random processes
    - » Most scientific data are acquired through a series of processes, each with some random error contribution!

# Uniform distribution

- ◆ Uniform PDF:  $u(x) = \text{constant} = 1 / (x_{\max} - x_{\min})$ 
    - basic PDF supplied on computers:  $u(0;1)=1$
    - Properties:  $\langle x \rangle = (x_{\max} + x_{\min}) / 2$ ,  $\sigma^2 = (x_{\max} - x_{\min})^2 / 12$
    - Any PDF can be obtained from  $u(x)$  by inverting its integral distribution  $F(x)$ 
      - » Can use this to generate random numbers for simulations, etc
- Choose uniform random number on  $[0,1]$  and use it to select  $x$  from  $F(x)$   
Example: Exponential distribution  $f(y)=\exp(-y)$   
Exercise: show  $y = -\ln(1-x)$  (with  $x$  uniformly distributed)  
is exponentially distributed.

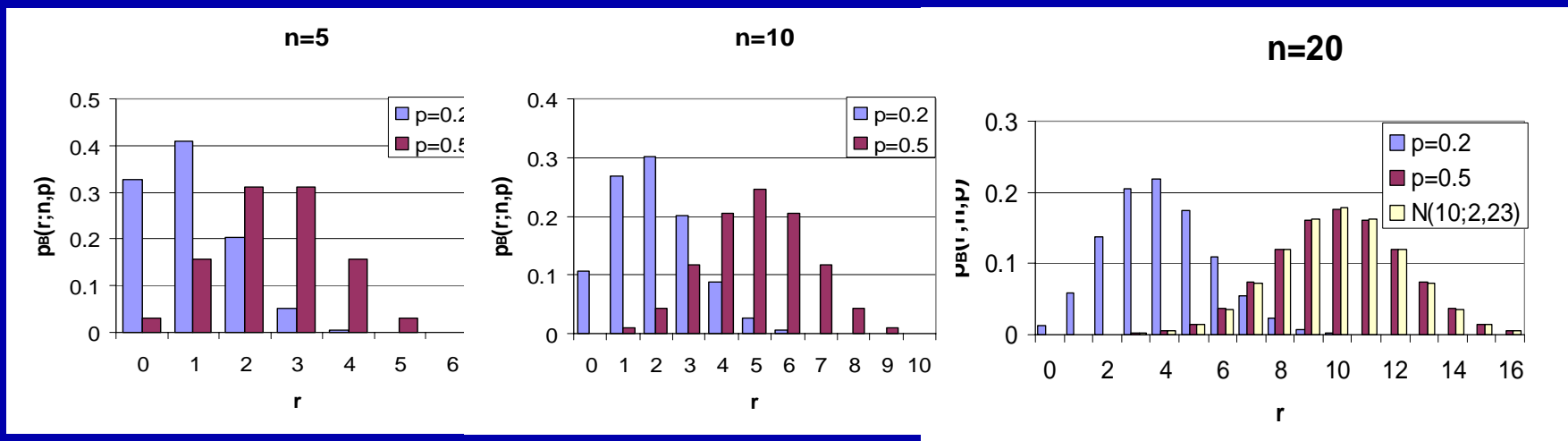


$F(x)$



# Binomial Distribution

- ◆ Applies to cases with **binary** outcomes like coin flips:
  - 0/1, heads/tails, T/F, yes/no, win/lose, success/failure
- ◆ *Discrete-valued* PDF gives  $P(n_{\text{SUCCESSES}} = \text{integer})$
- ◆ 2 parameters:  $p$  (success per trial = real),  $N_{\text{TRIALS}}$ 
  - $P(n \text{ successes followed by } (N-n) \text{ failures})$   
 $= p^n (1-p)^{N-n}$  (independent trials: multiply trial probs.)
  - But we don't care about **order** in which they occur:  
 number of permutations is  $N! / (n!(N-n)!)$   
 so  $P(n; p, N) = \{N! / (n!(N-n)!\} p^n (1-p)^{N-n}$
- ◆ Properties:  $\mu = Np$ ,  $\sigma^2 = Np(1-p) = \mu (1-p)$ ,  $\sim$  Gaussian for large  $Np$



# Poisson distribution

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- ◆ Limiting case of binomial distribution for  $p \rightarrow 0$
- ◆ only 1 parameter: mean value  $\mu$   
 $P(n \text{ successes} \mid \mu \text{ expected}) = (1/n!) \mu^n \exp(-\mu)$   
 $n$  is integer;  $\mu$  can be real
- ◆ Properties:  
variance  $\sigma^2 = \mu$ , so standard deviation  $\sigma = \text{sqrt}(\mu)$
- ◆ Applies when *Poisson assumptions* are valid:
  1.  $P(\text{event})$  in interval  $\delta x$  is *proportional to*  $\delta x$ :  $p = g\delta x$
  2. Occurrence of an event in an interval  $\delta x_j$  is *independent* of events or absence of events in any other non-overlapping interval  $\delta x_k$
  3. For sufficiently small  $\delta x$ , there can be at most 1 event in  $\delta x$

# Example of a Poisson Process

## ◆ Bubbles in a bubble chamber track

Prob of 1 bubble in  $\delta x$ :  $p_1(\delta x) = g\delta x$  (from #1)

Prob of 0 bubbles in  $\delta x$ :  $p_0(\delta x) = 1 - p_1 = 1 - g\delta x$  (from #3)

$p_0(x + \delta x) = p_0(x) \cdot p_0(\delta x) = p_0(x)(1 - g\delta x)$  (from #2)

$$\therefore \frac{p_0(x + \delta x) - p_0(x)}{\delta x} = -g$$

$$p_0(x) \rightarrow \frac{dp_0}{dx} = -gp_0$$

Solution:  $p_0(x) = e^{-gx}$  So  $p_0(x) = \text{exponential distribution}$

Prob of exactly  $r$  bubbles in  $x + \delta x$ :

$p_r(x + \delta x) = p_r(x) \cdot p_0(\delta x) + p_{r-1}(x) \cdot p_1(\delta x)$  (from #3)

$$\therefore \frac{p_r(x + \delta x) - p_r(x)}{\delta x} \rightarrow \frac{dp_r}{dx} = -gp_r(x) + gp_{r-1}(x)$$

Solution:  $p_r(x) = \frac{1}{r!} (gx)^r e^{-gx} = \text{Poisson distribution } (\mu = gx)$

# Gaussian (Normal) distribution

- ◆ Gaussian = famous "bell-shaped curve"
    - Describes IQ scores, number of ants in a colony of a given species, wear profile on old stone stairs...
- All these are cases where:
- deviation from norm is equally probable in either direction
  - Variable is continuous (or large enough integer to look continuous - far from the "wall" at zero)

- ◆ *Real-valued* PDF:  $f(x) \rightarrow -\infty < x < +\infty$

$$N(x; \mu, \sigma) = (1/\sqrt{2\pi\sigma^2}) \exp[-(x-\mu)^2/2\sigma^2]$$

- ◆ 2 independent parameters:  $\mu$ ,  $\sigma$  (central location and width)

- ◆ Properties:

Symmetrical, mode at  $\mu$ ,  
median=mean=mode, Inflection points at  $\pm\sigma$

Cumulative distribution :

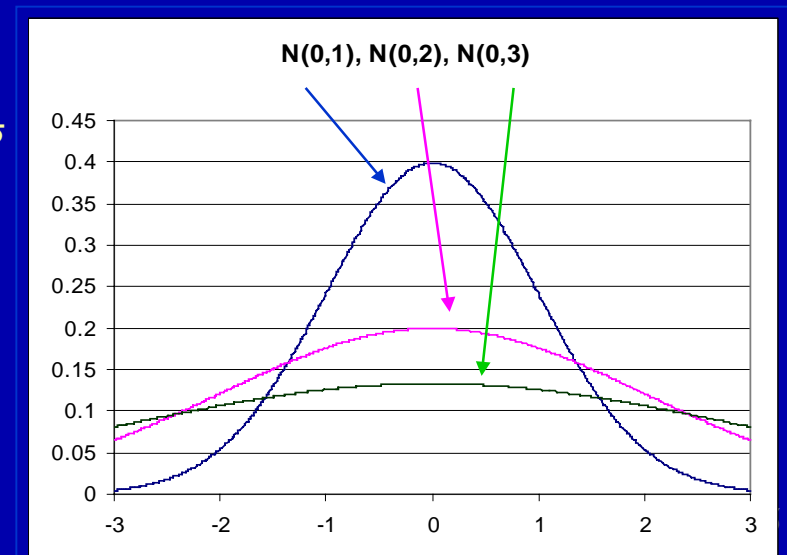
$$\int_{-\infty}^x n(x; 0, 1) dx = \text{erf}(x)$$

Area (probability of observing event) within:

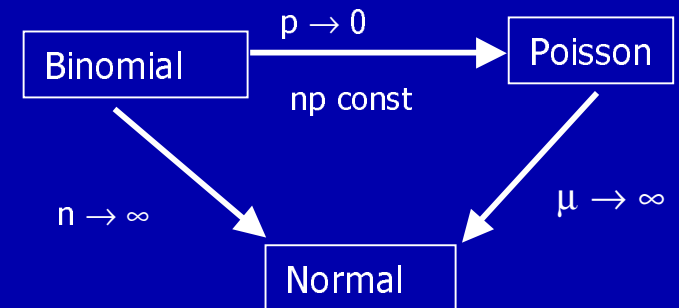
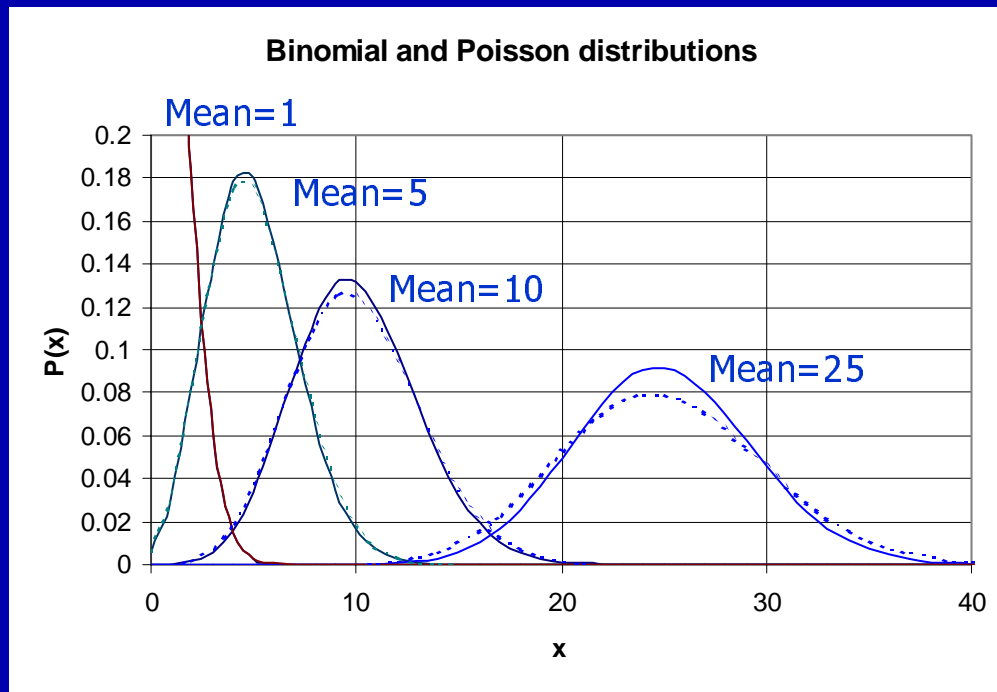
$$\pm 1\sigma = 0.683 = \text{erf}(1) - \text{erf}(-1)$$

$$\pm 2\sigma = 0.955 = \text{erf}(2) - \text{erf}(-2)$$

For larger  $\sigma$ , bell shaped curve becomes wider and lower (since area = 1 for any  $\sigma$ )



# Binomial, Poisson, Gaussian



Shown above:

- Binomial for 100 trials,  $p=0.01, 0.05, 0.10, 0.25$  (solid)
- Poisson for  $\mu = 1, 5, 10, 25$  (dashed line)

Poisson is broader and has peak slightly below  $\mu$

Both become similar to Gaussian  $N(\mu, \sigma=\sqrt{\mu})$  as mean value gets larger  
(Gaussian would be indistinguishable from Poisson for mean=25 on this plot)



# Why the Normal Distribution is important...

## ◆ *Central Limit Theorem:*

Given N **independent** random variables  $x_k$ , each with mean  $\mu_k$  and variance  $\sigma_k$  specified (but *not* details of individual PDF's), the random variable  $z = \sum x_k$  has

$$\mu_z = \sum \mu_k \text{ and } \sigma_z^2 = \sum \sigma_k^2,$$

and for  $N \rightarrow \infty$ , its PDF will be **Gaussian**, i.e.  $p(z) = N(\mu_z, \sigma_z)$

$$(\sum x_k - \sum \mu_k) / \text{sqrt}[\sum \sigma_k^2] = n(x; 0, 1)$$

## ◆ Applies to: any situation with real-valued result where several *independent* processes add: additive errors. Examples:

- Random walk of 100 steps. Each step is independent of others, any probability distribution for direction and length of each step (but  $\mu, \sigma^2$  known).
- To make a simple Gaussian random number generator, just take sum of 12 standard uniformly distributed numbers:

$$x = \sum (u_k - 6); \quad x \text{ will be distributed } \sim n(x; 0, 1)$$

(recall:  $u(0;1)$  has  $\mu = 0.5, \sigma^2 = 1/12$ )

## ◆ Parameters $\mu, \sigma$ are **independent** (and converse: if a random variable has $\mu, \sigma$ independent, it is normal).

Given N random numbers  $x_k$  drawn from a normal distribution,

the sample mean  $\mu = (1/N) \sum x_k$

and sample variance  $s^2 = \sum \sigma_k^2 / (N-1)$

are *independent statistics*

# Applications to counting

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- ◆ Errors in single counts
  - CR counts are a Poisson process, so  $\sigma_k^2 = N$ ,  $\sigma_k = \sqrt{N}$
- ◆ Errors on histogram bins contents
  - In/out of bin = binomial process, so  $\sigma_k^2 = Np_k(1-p_k)$   
where  $p_k = n_k/N$
  - Poisson approximation  $\sigma_k = \sqrt{n_k}$  is valid for  $n_k > 10$
- ◆ Significance of deviations from expectation

# Significance of deviations from expectation

## Example: counting statistics and limits of detectability

- ◆ How can we tell if a significant signal exists in the presence of background?

$N_T$  = observed counts in time  $T$

$N_B$  = background counts (separate experiment)

Then  $N_T = N_S + N_B$  where  $N_S$  = true signal counts

Assume  $T$  is long enough so all counts are "not small" ( $\gg 5$ )

Then expect  $N$ 's to be Poisson distributed ( $\sim$  Gaussian-distributed), with  $\sigma = \sqrt{N}$

$$N_S = N_T - N_B, \text{ so } \sigma_S^2 = \sigma_T^2 + \sigma_B^2$$

- Suppose there is *no real activity* present,  $N_S$  actually = 0

$$\sigma_T^2 = \sigma_B^2 \text{ so } \sigma_S^2 = 2 \sigma_B^2 \text{ or } \sigma_S = \sqrt{(2N_B)}$$

So we expect  $N_S$  to be drawn from a Gaussian distribution  $N(0, \sqrt{(2N_B)})$

- ◆ Define  $H_0$  = hypothesis that there is no activity present, all we are seeing is background
    - Reject  $H_0$  if  $N_T > N_C$  = "cut level" for decision
- How do we define  $N_C$  ?

# Significance of deviations from expectation

- ◆ Decide on a *significance level* = acceptable probability for being fooled by a random fluctuation

If we want, eg, <5% probability of false positive result, we must set  $N_C$  at the 5% tail of the Gaussian distribution.

- ◆ Example:  $H_0$  = "no radioactive decays from this sample"

No-sample run gives 6 counts, assumed to be background

$$\sigma_S = \sqrt{2N_B} = 3.5$$

Therefore if  $H_0$  = true, and we count the sample many times, we would get fewer than:

3.5 counts 68% of the time

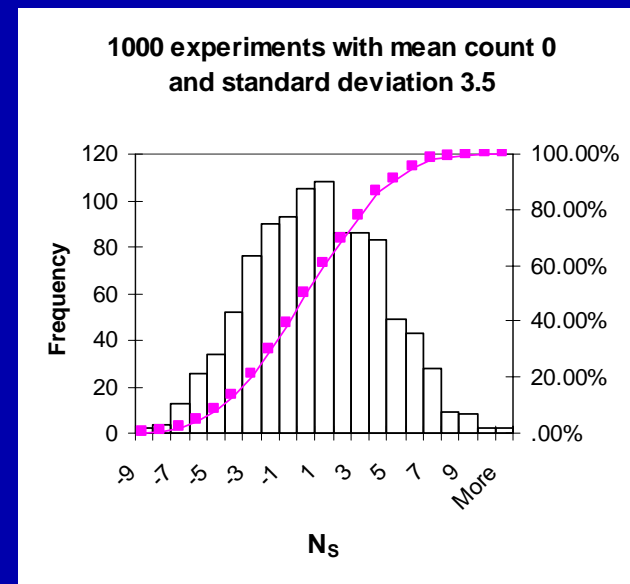
7 counts 95% of the time

10.5 counts 99.7% of the time

Another way to say it:

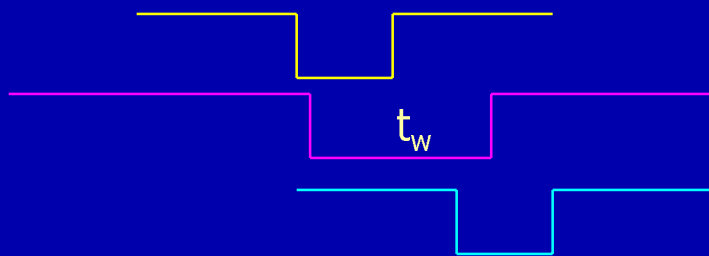
we can reject  $H_0$  at the 95%

**confidence level** if we observe  $N > 7$



# "Accidentals"

- ◆ **Accidentals** = Chance coincidences due to uncorrelated noise pulses which happen to arrive within the logic gate's time window



- Counter 1's pulse arrives (Average spacing is  $1/r_1$  sec)
- Logic gate opens a window (note delay)
- Counter 2's pulse arrives (Average spacing is  $1/r_2$  sec)

- ◆ If noise is truly random, then the fraction of each second occupied by available coincidence windows is

$$f_{\text{OCCUPIED}} = r_1 * t_w$$

where  $r_1$ =singles rate of counter 1, Hz;  $t_w$ =window width, sec

(This is equal to the probability that a randomly selected time lies within a coincidence window)

- ◆ The rate of 2-fold accidentals will thus be

$$r_{12} = r_2 * f_{\text{OCCUPIED}} = r_2 * r_1 * t_w \quad (\text{for } r_{1,2} * t \ll 1)$$